

Single Image Rolling Shutter Rectification

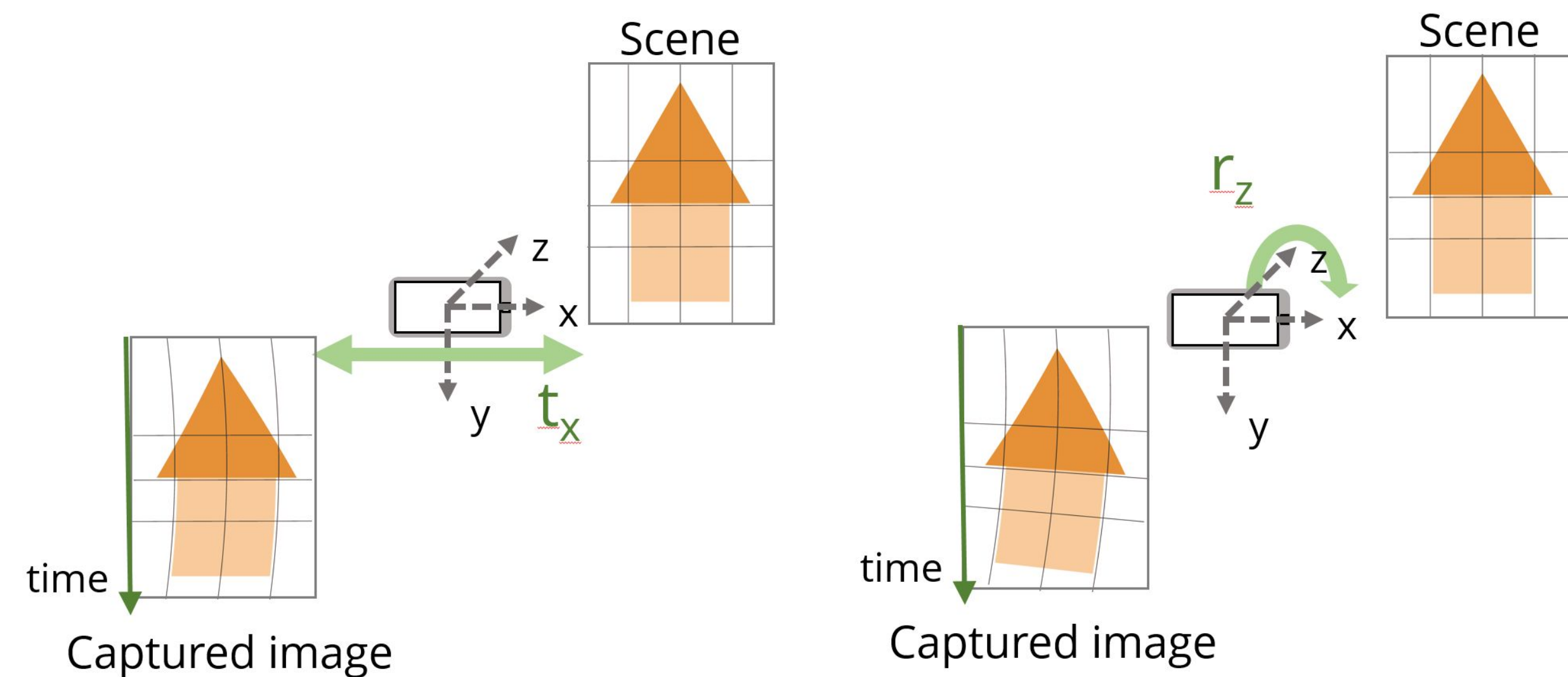
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apvijay.github.io



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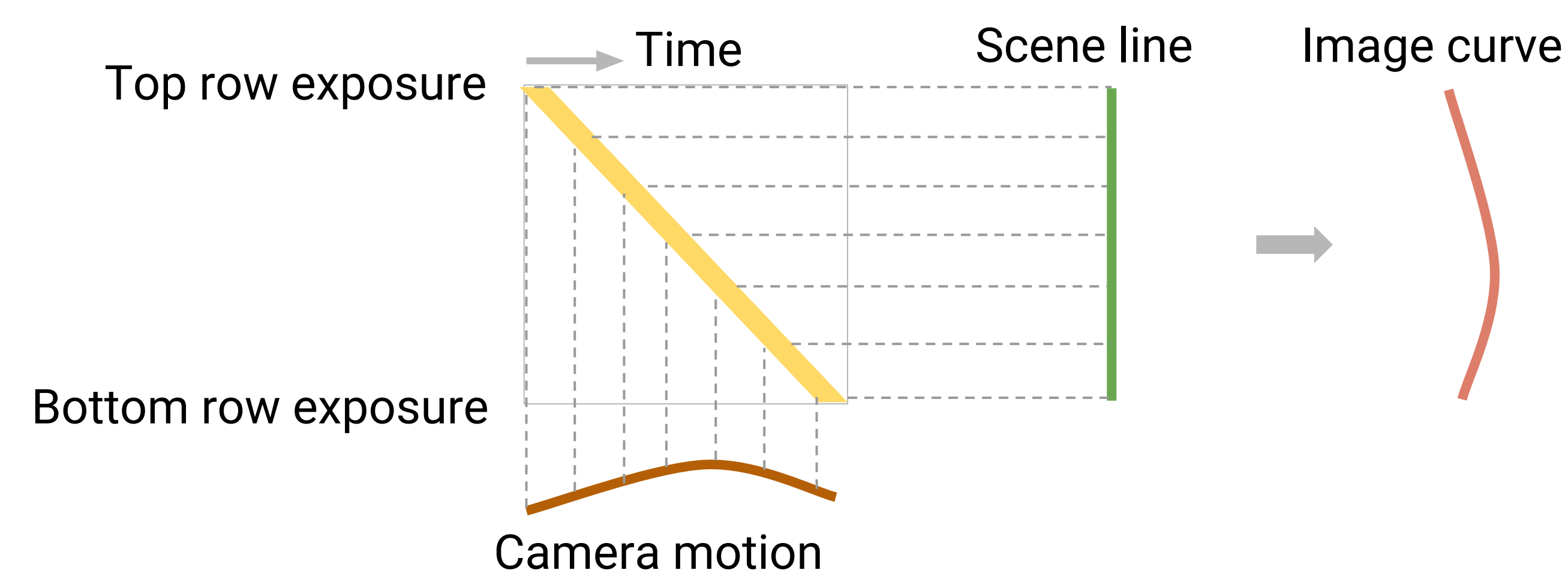
Correct Rolling Shutter Distortions From A Single Image



Most mobile phone (CMOS sensor) cameras employ row-wise light acquisition

Camera motion even during short exposure causes local geometric distortions known as the *rolling shutter effect*

Each image row is associated with a camera pose



Challenges

Lack of multiple images to exploit correspondences

What image features to extract to decode camera trajectory?

Polynomial motion model

For $i \in \{x, y, z\}$,

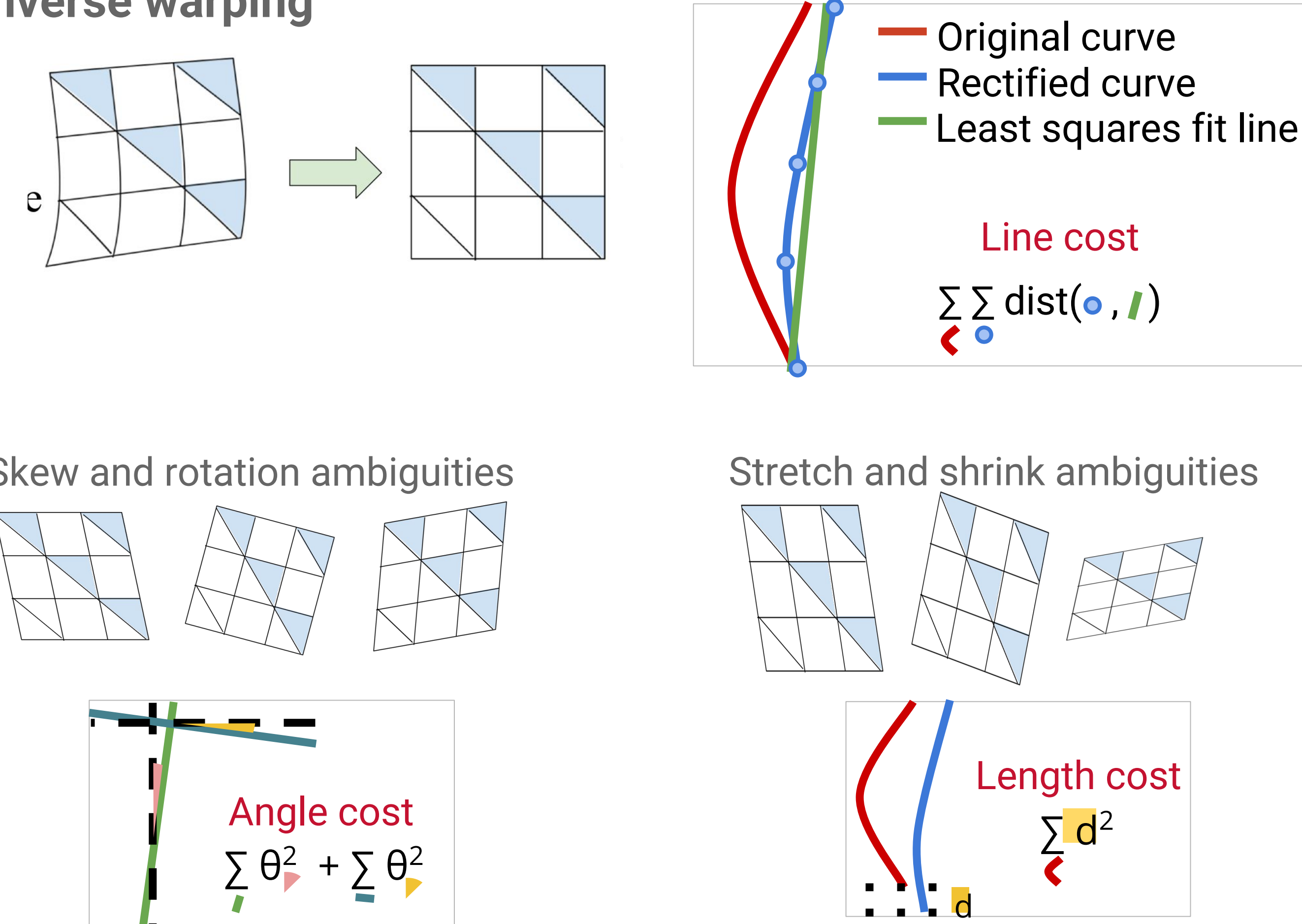
$$r_i(y) = \alpha_{i0} + \sum_{j=1}^n \alpha_{ij} \left(\frac{y-1}{M}\right)^j$$

y : row index $\in [1, M]$ M : number of rows

α_{ij} : j^{th} coefficient for the i^{th} axis motion

Geometry-Based Approach

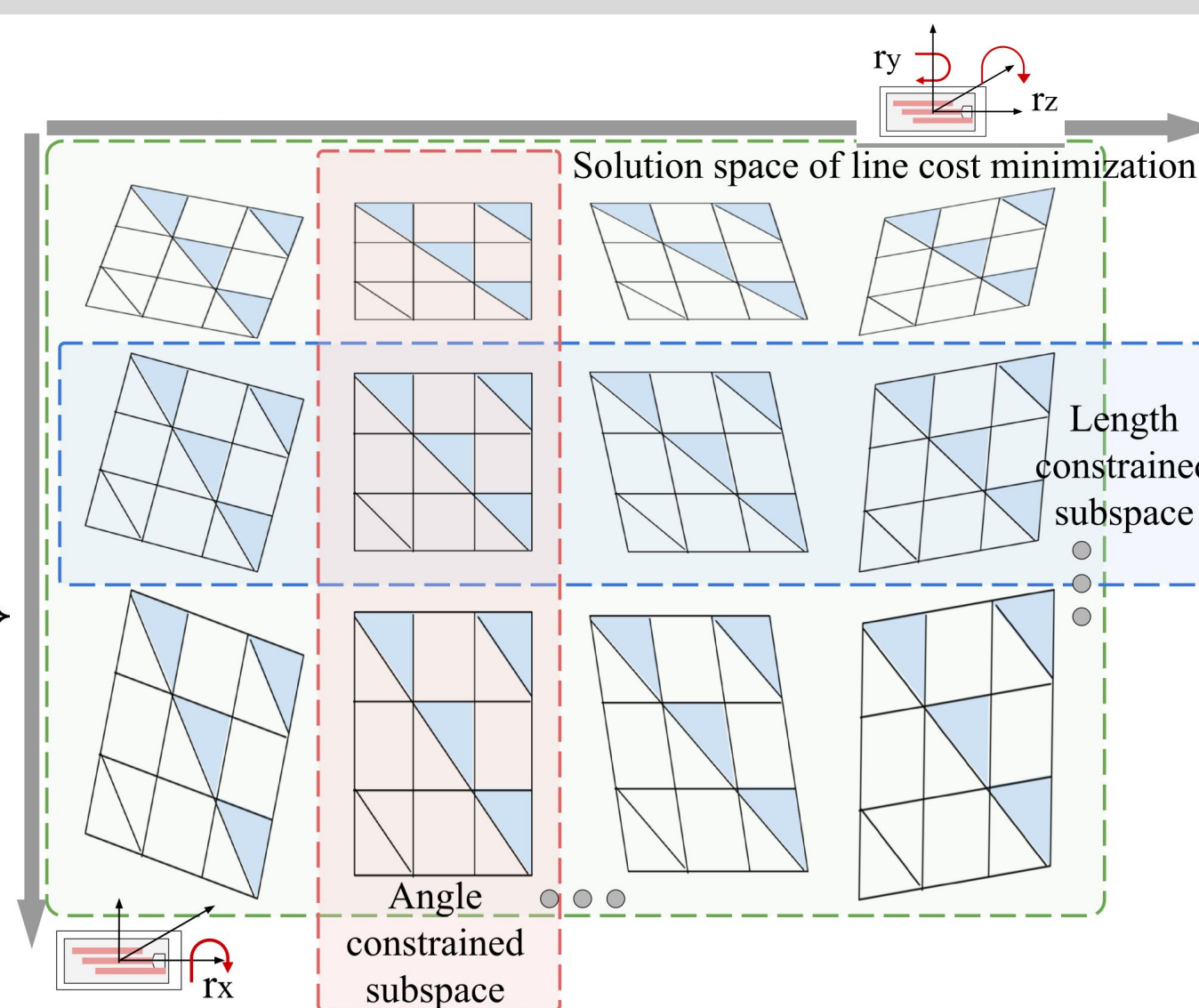
A desirable motion trajectory transforms curves to lines on inverse warping



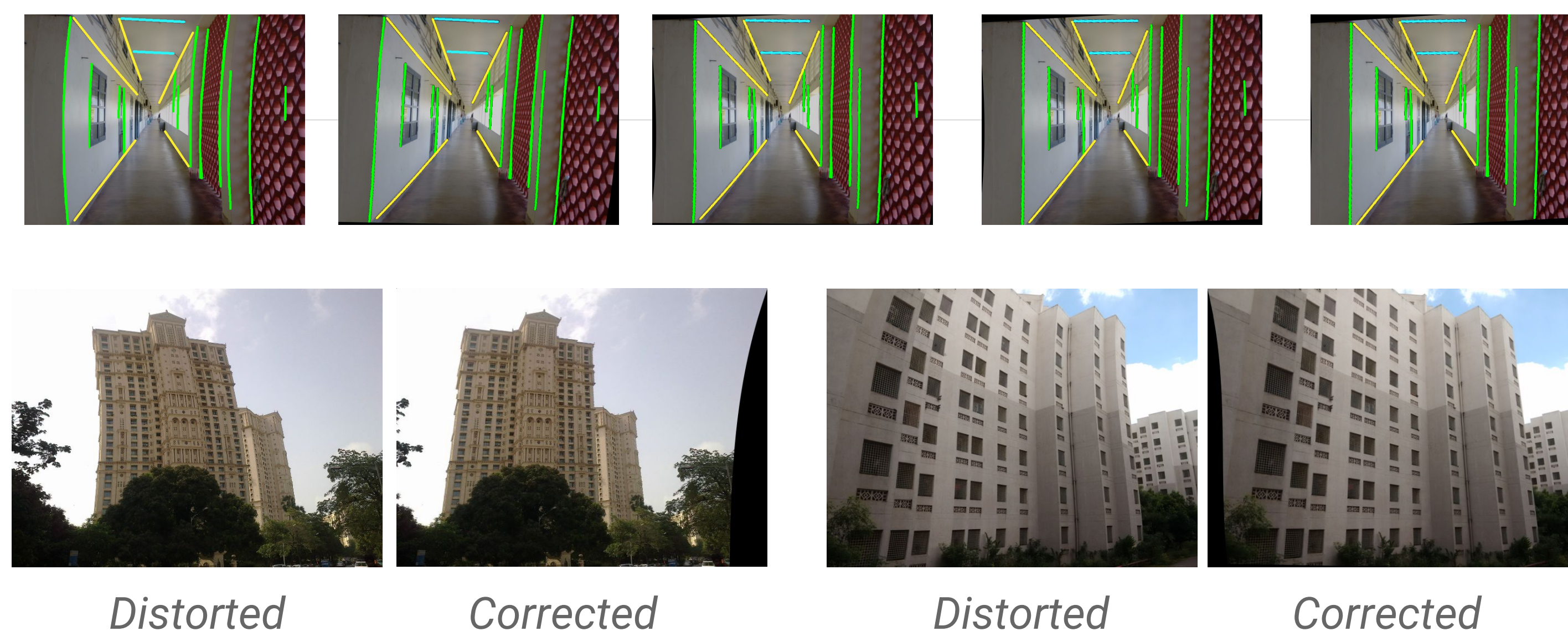
Estimate polynomial coefficients of motion that result in minimum line cost subject to desirability constraints

$$\{\hat{\alpha}_{ij}\} = \arg \min_{\alpha_{ij}} \{ \text{Line cost} \}$$

subject to $\begin{cases} \text{Angle cost} < \epsilon_1 \\ \text{Length cost} < \epsilon_2 \end{cases}$



Intermediate results over iterations



*Vijay Rengarajan, A.N. Rajagopalan, and R. Aravind, "From Bows to Arrows: Rolling Shutter Rectification of Urban Scenes," Proceedings of International Conference on Computer Vision and Pattern Recognition (CVPR), June 2016

Learning-Based Approach

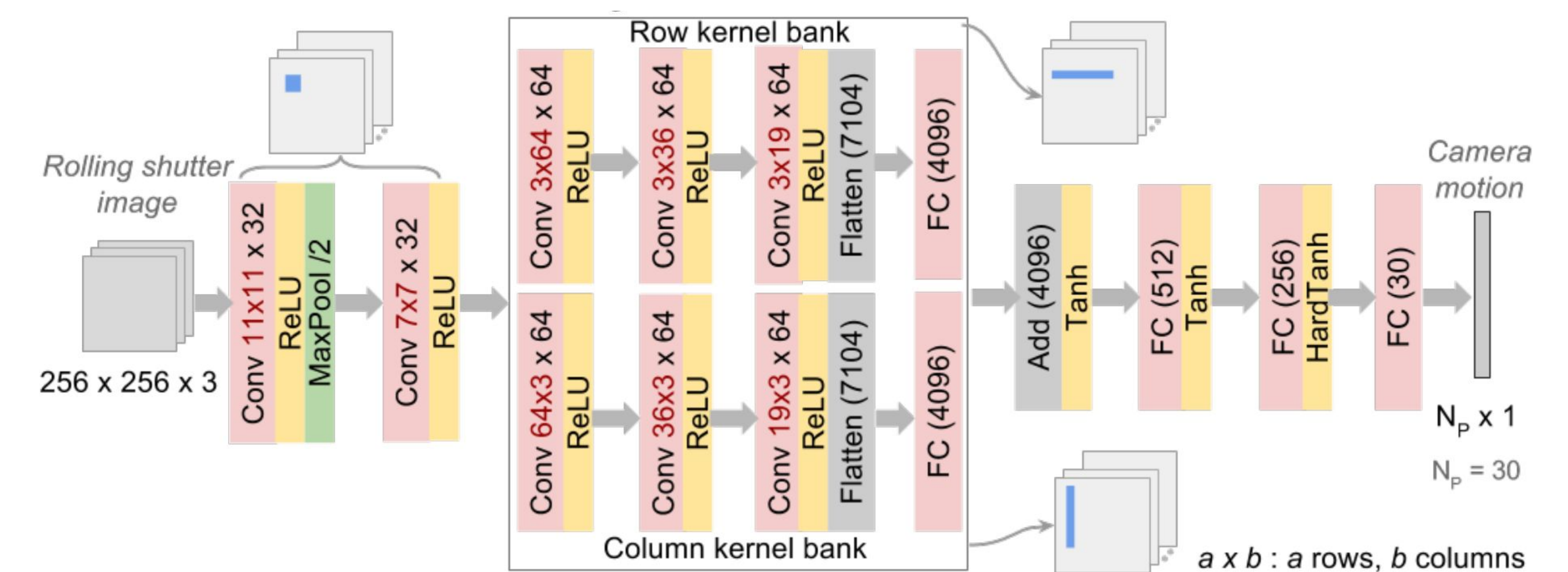
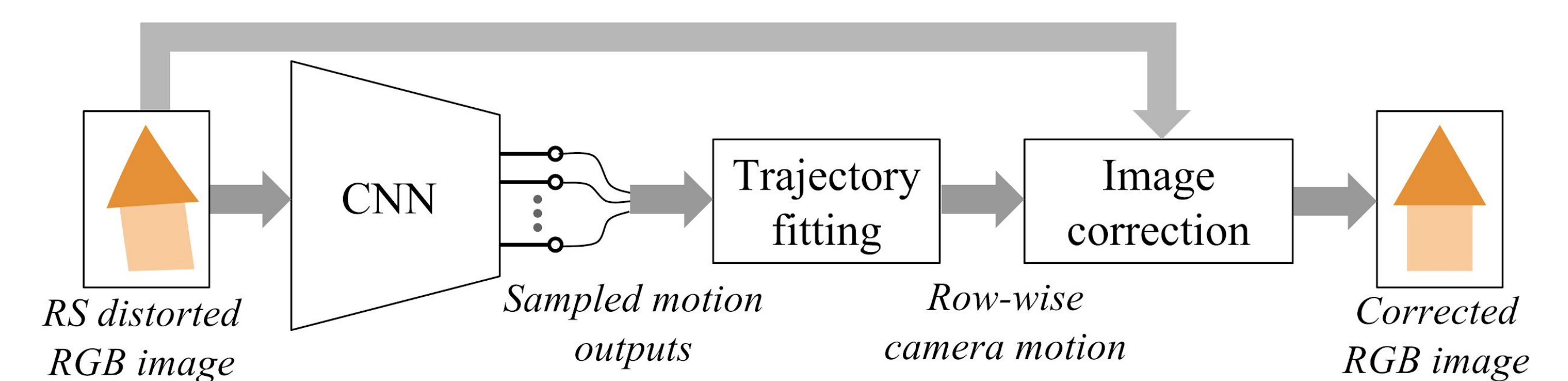
Use a CNN to map the distorted image space to the motion space

CNN input: Rolling shutter image (256x256 RGB)

CNN output: Motion values (15 tx samples, 15 rz samples corresponding to equally spaced rows)

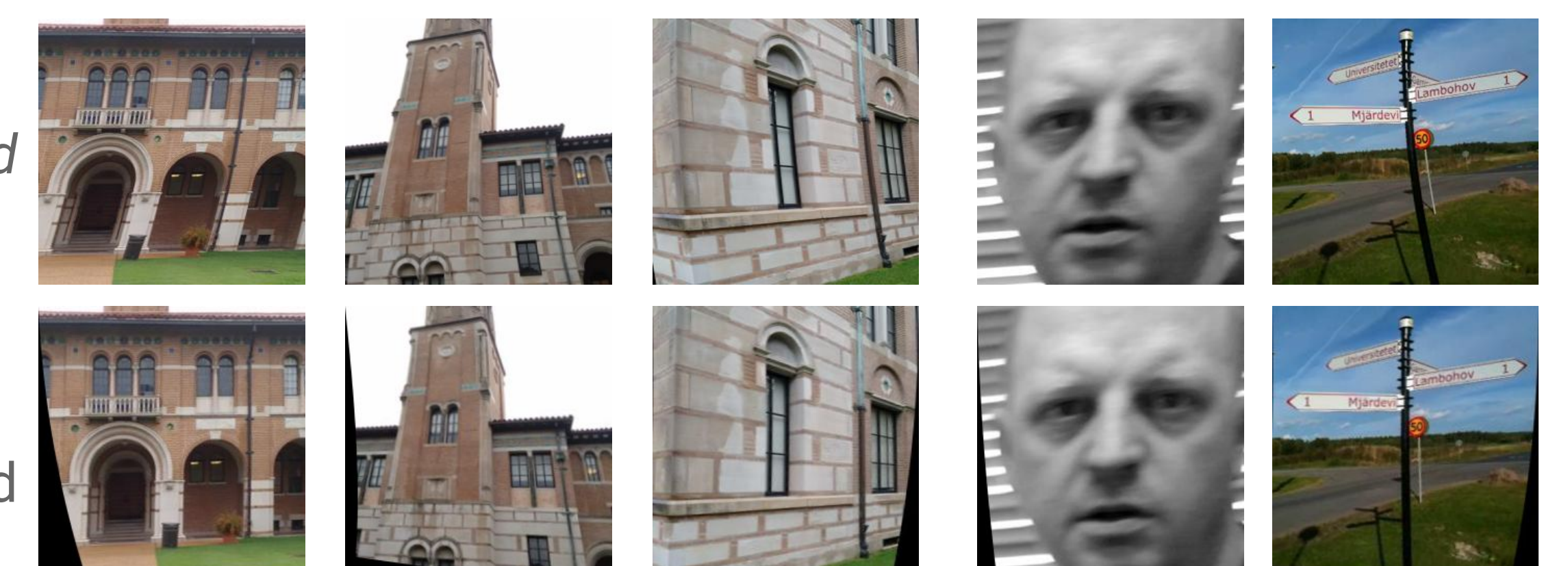
Fit a polynomial trajectory to get row-wise camera poses

Correct the distorted image using inverse warping



Distorted

Corrected



*Vijay Rengarajan, Yogesh Balaji, and A.N. Rajagopalan, "Unrolling the Shutter: CNN to Correct Motion Distortions," Proceedings of International Conference on Computer Vision and Pattern Recognition (CVPR), July 2017